

操作系统原理与设计

第11章文件系统的实现1

陈香兰

中国科学技术大学计算机学院

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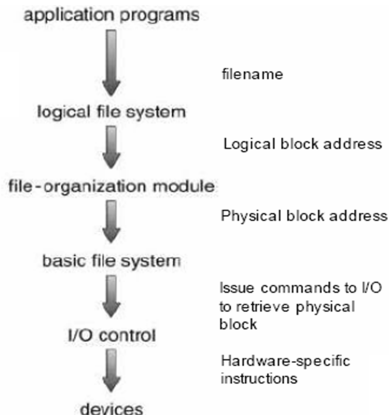
提纲

- 1 File-System Structure
- 2 FS Implementation
- 3 Directory Implementation
- 4 Allocation Methods
- 5 Free-Space Management
- 6 小结和作业

File-System Structure I

- File structure
 - Logical storage unit
 - Collection of related information
- File system resides on secondary storage (disks)
- File system organization
 - How the file system should look to the user
 - How to map the logical file system onto the physical secondary-storage devices
- File system organized into layers
- Layered File System

File-System Structure II



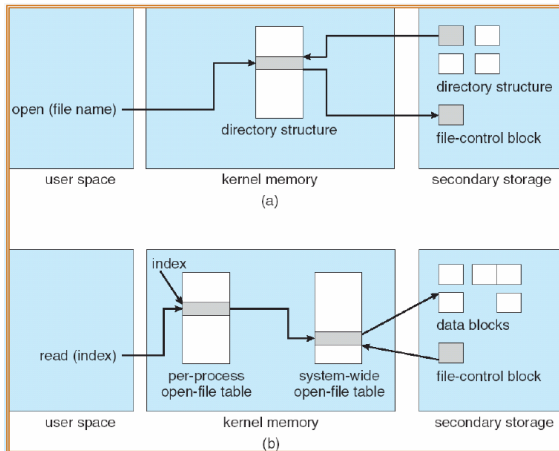
FS Implementation I

- structures and operations used to implement file system operation, OS- & FS-dependment
 - on-disk structures
 - in-memory structures
- on-disk structures
 - boot control block
 - to boot an OS from the partition (volume)
 - if empty, no OS is contained on the partition
 - volume control block
 - directory structure
 - per-file FCB

FS Implementation II

- in-memory information
 - used for both FS management and performance improvement via caching
 - data are loaded at mount time and discarded at dismount
 - structures include:
 - in-memory mount table
 - in-memory directory-structure cache
 - system-wide open-file table
 - per-process open-file table

In-Memory File System Structures



FCB

- A Typical File Control Block

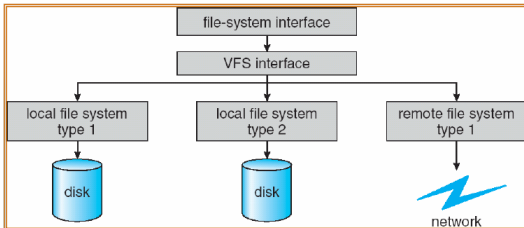
file permissions
file dates (create, access, write)
file owner, group, ACL
file size
file data blocks or pointers to file data blocks

partitions and mounting

- partition
 - raw (E.g. UNIX swap space & some database) VS. cooked
 - boot information, with its own format
 - boot image
 - boot loader unstanding multiple FSes & OSes
 - dual-boot
- root partition is mounted at boot time
- others can be automatically mounted at boot or manually mounted later

Virtual File Systems

- Virtual File Systems (VFS) provide an object-oriented way of implementing file systems.
- VFS allows the same system call interface (the API) to be used for different types of file systems.
- The API is to the VFS interface, rather than any specific type of file system.
- Schematic View of Virtual File System



Directory Implementation

- Linear list of file names with pointer to the data blocks.
 - simple to program
 - time-consuming to execute
- Hash Table – linear list with hash data structure.
 - decreases directory search time
 - collisions – situations where two file names hash to the same location
 - Fixed & variable size or chained-overflow hash table

Allocation Methods

- An allocation method refers to **how disk blocks are allocated** for files so that disk space is **utilized effectively** & files can be **accessed quickly**
 - ① Contiguous allocation
 - ② Linked allocation
 - ③ Indexed allocation
 - ④ Combined

1. Contiguous Allocation I

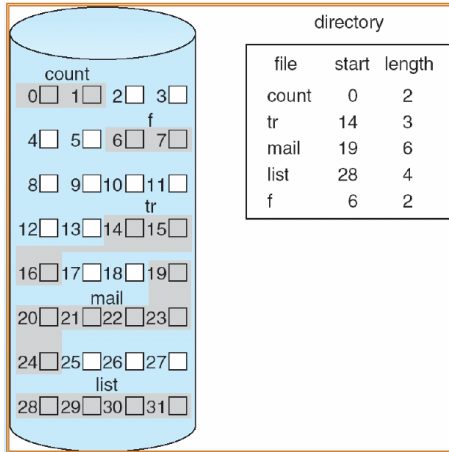
- Each file occupies a **set of contiguous** blocks on the disk
- Simple – directory entry only need
 - **starting location (block #)**
 - **& length (number of blocks)**
- Mapping from logical to physical

$$\text{LogicalAddress}/512 = Q \dots R$$

Block to be accessed = Q + starting address

Displacement into block = R

1. Contiguous Allocation II



1. Contiguous Allocation III

- Advantages:
 - Support **both random & sequential** access
 - Start block: b ;
Logical block number: i
 \Rightarrow physical block number: $b + i$
 - **Fast** access speed, because of short head movement
- Disadvantages:
 - **External fragmentation**
 - **Wasteful of space** (dynamic storage-allocation problem).
 - **Files cannot grow**,
or File size must be known in advance.
 \Rightarrow **Internal fragmentation**

Extent-Based Systems

- Many newer file systems (I.e. Veritas File System) use a **modified contiguous allocation scheme**
- Extent-based file systems allocate disk blocks in extents
- An extent is a contiguous block of disks
 - Extents are allocated for file allocation
 - A file consists of one or more extents.

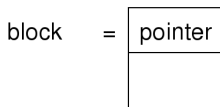
2. Linked Allocation I

- Each file is a linked list of disk blocks: blocks may be scattered anywhere on the disk.
- Directory
 - First block
 - Last block

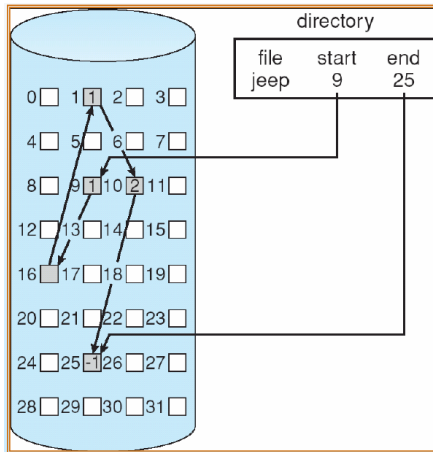
- Two types

- 1 **Implicit**
- 2 **Explicit**

1 Implicit



2. Linked Allocation II



2. Linked Allocation III

- **Allocate as needed, link together**
 - Simple – need only starting address
- Free-space management system – **no waste of space**
- Disadvantage:
 - **No random access**
 - **Link pointers need disk sapce**
 - E.g.: 512 per block, 4 per pointer $\Rightarrow 0.78\%$
 - Solution: **clusters**
 - \Rightarrow disk throughput \uparrow
But internal fragmentation \uparrow

2. Linked Allocation IV

- Mapping

$$512 - 1 = 511$$

$$\text{LogicalAddress}/511 = Q \dots R$$

Block to be accessed is the Q^{th} block in the linked chain of blocks representing the file.

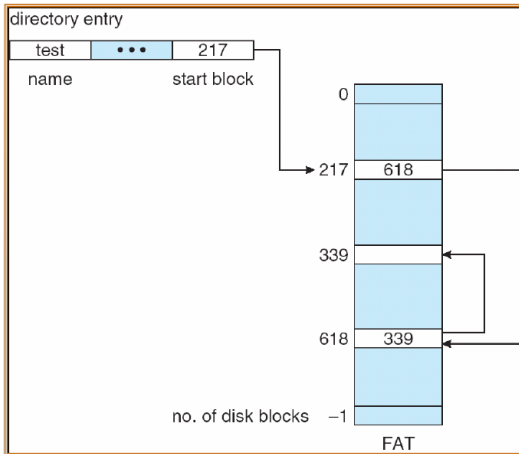
Displacement into block = $R + 1$

- **How to reduce searching time?**

File-Allocation Table (FAT) I

- FAT: Explicit linked allocation
Disk-space allocation used by MS-DOS and OS/2
 - A section of disk at the beginning of each partition is set aside to contain the table
 - Each disk block, an entry, contains the index of the next block in the file
 - Last block entry, end-of-file
 - Unused, 0
- Directory entry contains the first block number
- Now support random access, but still not very efficient
- May result in a significant disk head seeks: Cached FAT

File-Allocation Table (FAT) II



File-Allocation Table (FAT) III

- Compute FAT size

Disk space : 80GB

Block size : 4KB

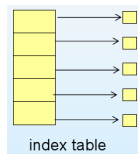
Total block number : $80 \times 2^{30} / 2^{12} = 5 \times 2^{22}$

$$4 \times 2^{22} = 2^{24} < 5 \times 2^{22} < 8 \times 2^{22} = 2^{25}$$

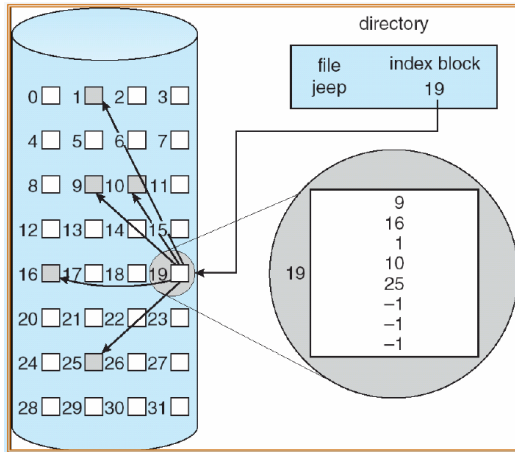
- Length of each FAT entry?
- Length of FAT?

3. Indexed Allocation I

- Brings all pointers together into one location – the index block.
 - Each file has its own index block
 - Index block address is stored in directory entry.
 - Each block is an array of pointers
 - Logical block number i , the i^{th} pointer
- Logical view. index table



3. Indexed Allocation II



3. Indexed Allocation III

- Need index table
- Advantage:
 - **Random** access
 - Dynamic access **without external fragmentation**
- Disadvantage:
 - have **overhead** of index block.
 - File **size limitation**, since one index block can contains limited pointers

3. Indexed Allocation IV

- Mapping from logical to physical
 - maximum file size 256K words & block size of 512 words.

$$256K/512 = 2^{18}/2^9 = 2^9 = 512$$

We need only 1 block for index table.

$$\text{LogicalAddress}/512 = Q \dots R$$

Q = displacement into index table

R = displacement into block

- **How to support a file of unbounded length? (suppose block size of 512 words).**
 - 1 linked scheme
 - 2 multi-level index scheme

3. Indexed Allocation V

① Linked scheme

- Link blocks of index table (no limit on size).
- Mapping

$$LogicalAddress / (512 \times 511) = Q_1 \dots R_1$$

Q_1 = block of index table

R_1 is used as follows:

$$R_1 / 512 = Q_2 \dots R_2$$

Q_2 = displacement into block of index table

R_2 displacement into block of file:

3. Indexed Allocation VI

- ② Two-level index (maximum file size is 512^3)

$$\text{LogicalAddress} / (512 \times 512) = Q_1 \dots R_1$$

Q_1 = displacement into outer-index

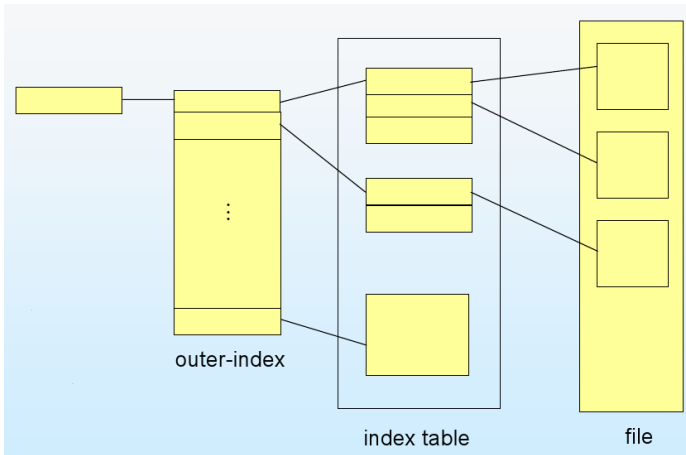
R_1 is used as follows:

$$R_1 / 512 = Q_2 \dots R_2$$

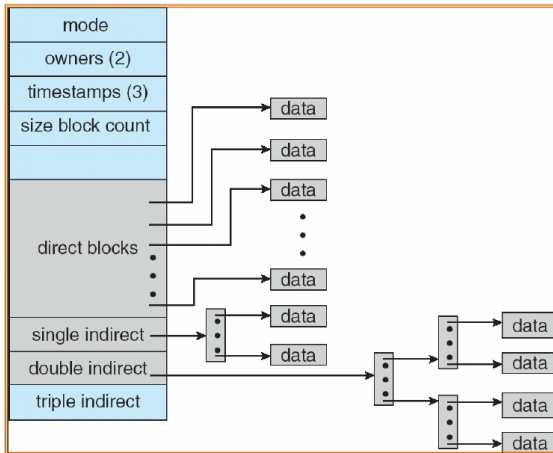
Q_2 = displacement into block of index table

R_2 displacement into block of file:

3. Indexed Allocation VII



4. Combined Scheme: UNIX (4K bytes per block) |



4. Combined Scheme: UNIX (4K bytes per block) II

- if 4KB per block, 4B per entry

$$\text{Direct blocks} = 10 \times 4KB = 40KB$$

$$\text{Number of entries per block} = 4KB/4B = 1K$$

$$\text{Single indirect} = 1K \times 4KB = 4MB$$

$$\text{Double indirect} = 1K \times 4MB = 4GB$$

$$\text{Triple indirect} = 1K \times 4GB = 4TB$$

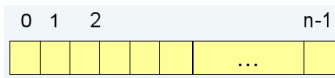
Maximnm file size = ?

Free-Space Management

- Disk Space
 - limited
- Free space management
 - To keep track of free disk space
 - Free-space list
- Algorithms
 - ① Bit vector
 - ② Linked list
 - ③ Grouping (成组链接法)
 - ④ Counting

1. Bit vector I

- Free-space list is implemented as a **bit map** or **bit vector**
 - **Each block** \longleftrightarrow **1 bit**
 - 1=free;
 - 0=allocated
 - E.g.: Bit vector (n blocks)



$$bit[i] = \begin{cases} 1 \Rightarrow block[i] \text{ free} \\ 0 \Rightarrow block[i] \text{ occupied} \end{cases}$$

1. Bit vector II

- **Block number calculation**

- Base unit:
 - word (**16** bits) or other
- n blocks:
 - bit map length = $(n + 15)/16$
- If first K words is 0, & $(K + 1)^{th}$ word > 0 ,
the first $(K + 1)^{th}$ word's first 1 bit has offset L ,
then

first free block $\# = ?$

first free block number $N = K \times 16 + L$

1. Bit vector III

- **Simple**

- Must be kept on disk

Bit map requires extra space, Example:

block size = 2^{12} bytes

disk size = 2^{30} bytes (1 gigabyte)

$n = 2^{30}/2^{12} = 2^{18}$ bits (or 32K bytes)

- Solution: Clustering
- **Efficient** to get the first free block or n consecutive free blocks, **if we can always store the vector in memory.**
 - BUT Copy in memory and disk may differ.
E.g. $\text{bit}[i] = 1$ in memory & $\text{bit}[i] = 0$ on disk

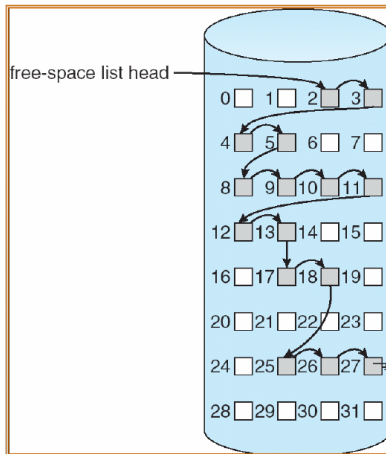
1. Bit vector IV

- Solution:
 - Set $\text{bit}[i] = 1$ in memory.
 - Allocate $\text{block}[i]$
 - Set $\text{bit}[i] = 1$ in disk
- Need to protect:
 - Pointer to free list
 - Bit map

2. Linked Free Space List on Disk I

- link together all the free disk blocks
 - First free block
 - Next pointer
- Not efficient
- Cannot get contiguous space easily
- No waste of space

2. Linked Free Space List on Disk II



3. Grouping

- To store the addresses of n free blocks (a group) in the first free block
 - First $n-1$ group members are actually free
 - Last one contain the next group
 - And so on
- E.g.: UNIX

4. Counting

- Assume:
 - Several contiguous blocks may be allocated or freed simultaneously
- Each = first free block number & a counter (number of free blocks)
- Shorter than linked list at most time, counter > 1

小结

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谢谢！